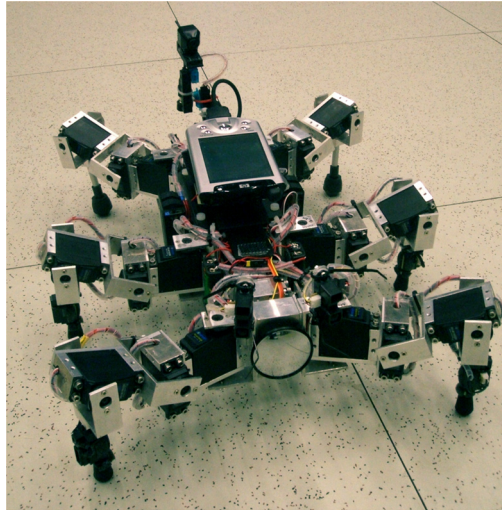


AMOS-WD06



Developer Manoonpong, Poramate and Pasemann, Frank
Fraunhofer Institut Autonome Intelligente Systeme (AIS), Germany
poramate.manoonpong, frank.pasemann@ais.fraunhofer.de
www.ais.fraunhofer.de/INDY/

Points of interest

- Reactive behavior, e.g. obstacle avoidance behavior
- Omni-directional walking driven by the modular neural controller
- Demonstration platform for evolved modular neural control

Technical details

Type of machine 6-legged walking machine with a backbone joint and an active tail

Size & weight L: 40cm x W: 30cm x H: 12cm; 4.2kg

Preferred substrate flat area with a corner and some obstacles